# Current-Driven Wire Planning for Electromigration Avoidance in Analog Circuits



Göran Jerke AE / Design of Integrated Circuits Robert Bosch GmbH Reutlingen, Germany

Email: goeran.jerke@ieee.org



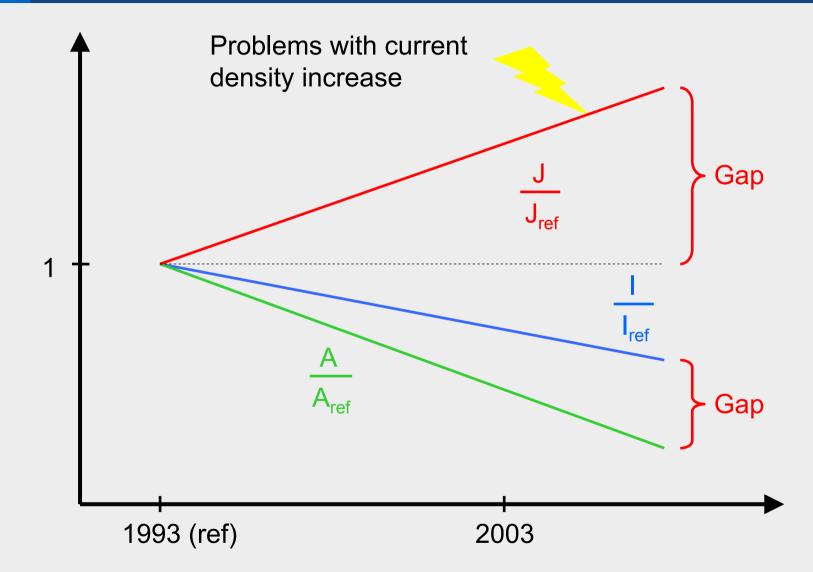
Jens Lienig Faculty of Electrical Engineering and Information Technology Dresden University of Technology Dresden, Germany

Email: jens@ieee.org

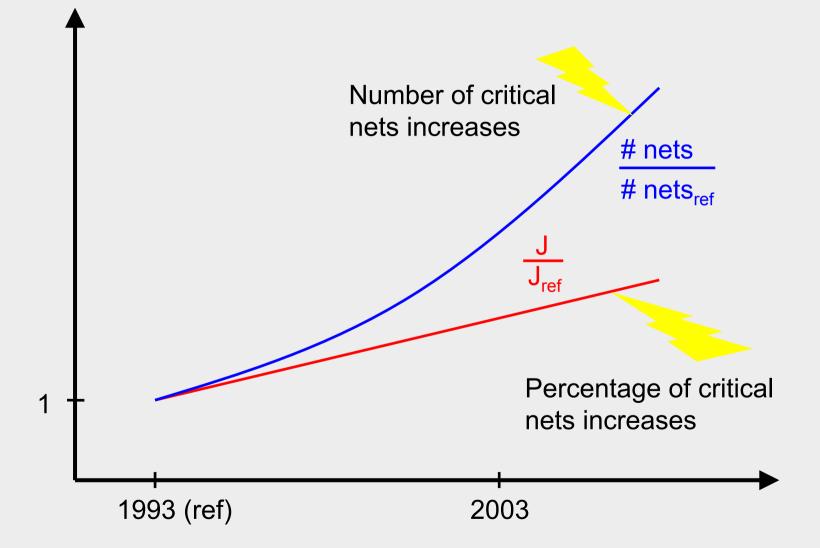
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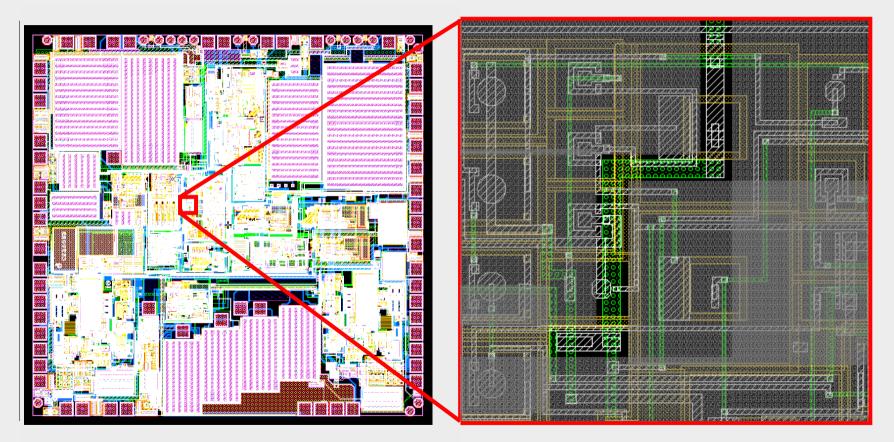
#### **Motivation**



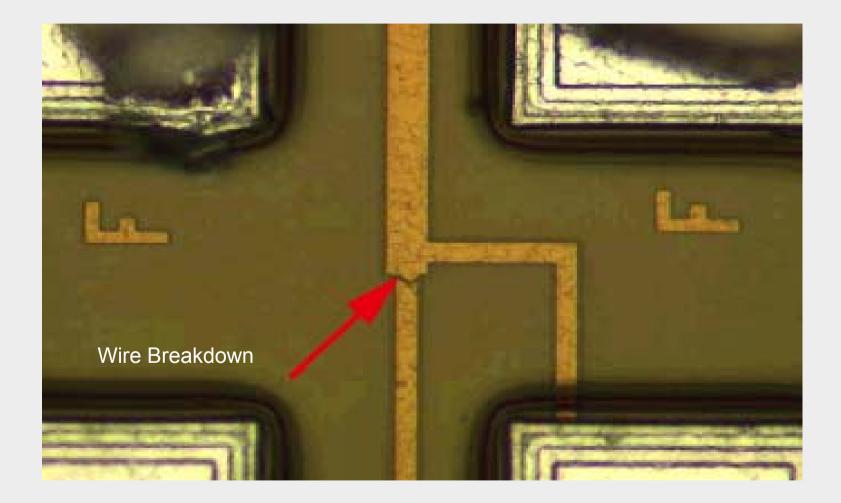
#### Motivation (cont.'d)



Current density critical nets exist in top level cells and block level cells



## **Physics of Electromigration**



#### What is Current-Driven Wire Planning?

# Layout Design

Topology-driven

## Constraints

- Design rule correctness

# **Optimization Goals**

- Min. net length
- Max. percentage of finished nets

Performance-driven

- Design rule correctness
   + Performance
- Min. delay and skew
- Min. number of buffers

Reliability-driven (Current-driven)

- Design rule correctness
   + Performance
- + Reliability

- Max. reliability
- Max. manufacturability
- Max. electromagnetic compatibility

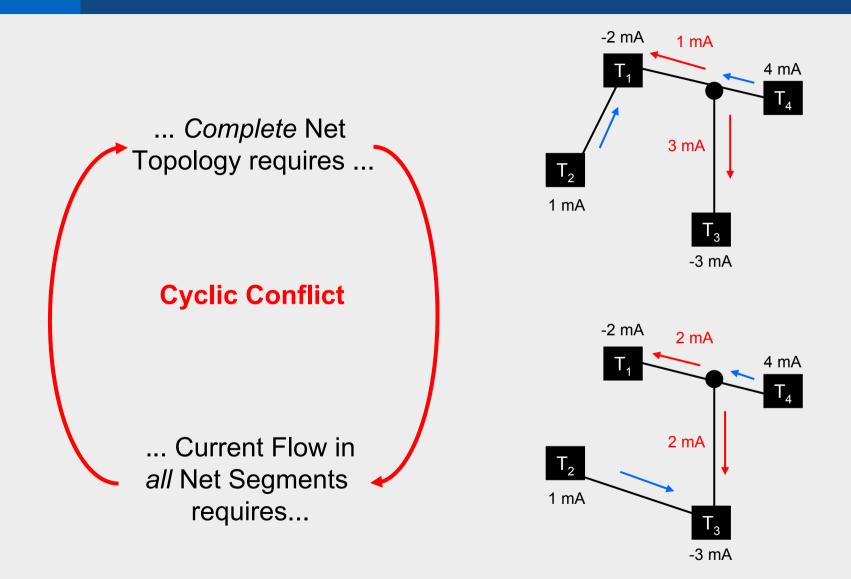
## What is Current-Driven Wire Planning ? (cont.'d)

- Current flow is our primary guidance parameter for wire planning
- Definition "Current-Driven Wire Planning":

Current-driven wire planning is wire planning *controlled* by the current flow to be expected in various net segments.

 Optimization goal is to minimize the used routing area while ensuring interconnect reliability

#### The Cyclic Nature of Current-Driven Wire Planning



#### **Previous Works**

- Electromigration physics: [Black68], [D'Heurle71], [Black83]
- Wire width adjustment after routing (power routing): [Syed82], [Rothermel83], [Moulton83], [Haruyama87], [Chowdhury87], [Mitsuhashi92]
- Current-driven routing: Steiner point insertion [Adler00a], [Adler00b], [Lienig02]

## **Previous Solution: Wire Width Adjustment After Routing**

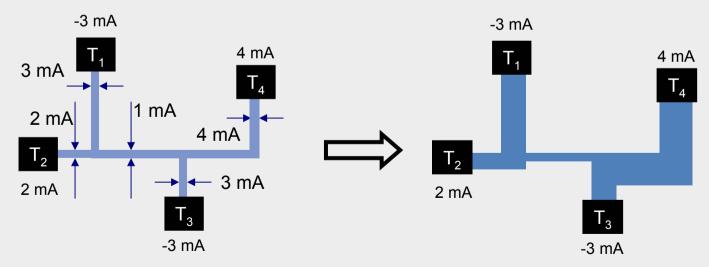
**Given:** Layout topology of a routed net

**Objective:** Adjust wire and via cross-sections according to current flow in net segments

**Algorithm:** 1. Route net with arbitrary wire width(s)

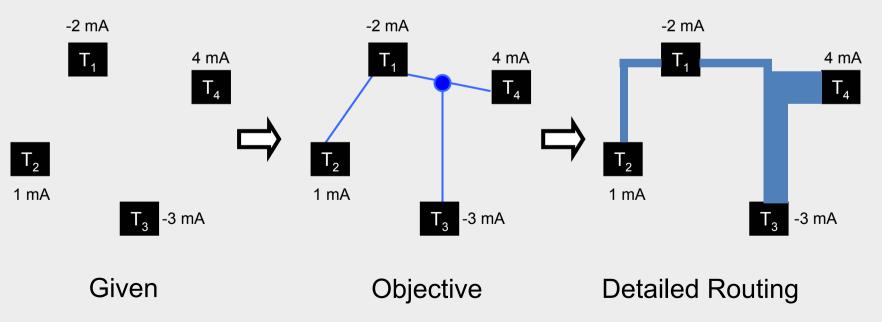
2. Calculate all branch currents

3. Adjust cross section of wires and vias / via arrays

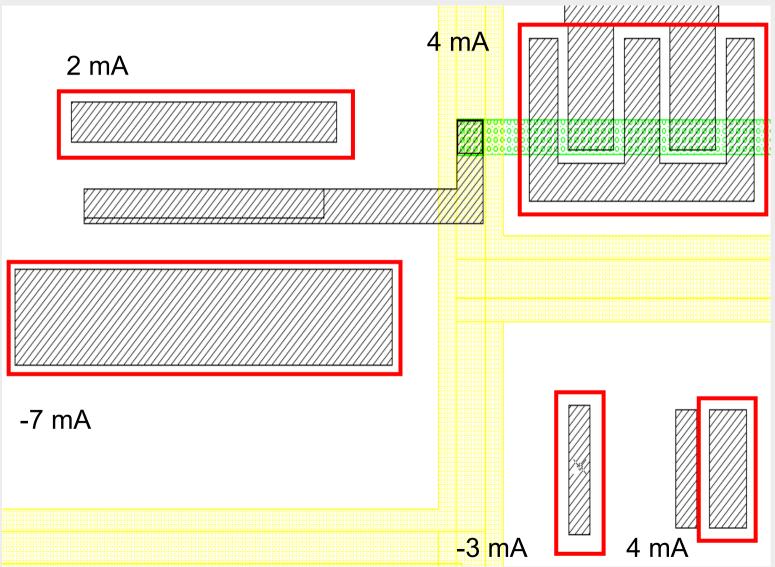


## **Our Solution: Current-Driven Wire Planning Prior to Routing**

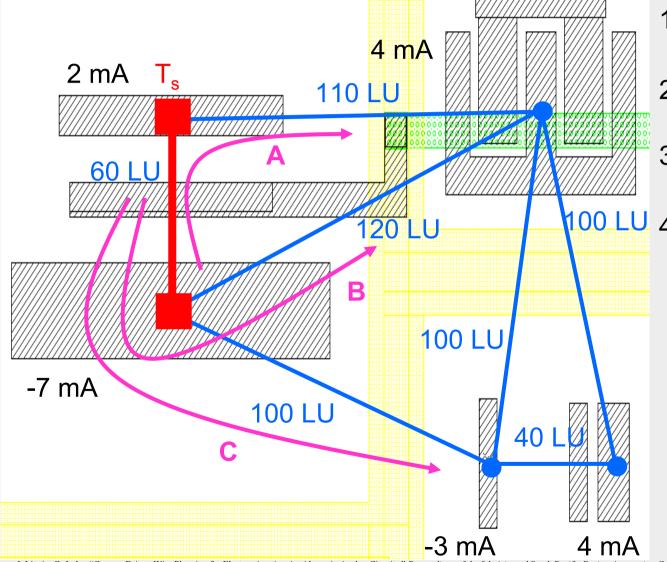
- **Given:** Net terminals with currents
- **Objective:** Obtain a list of net segments with an optimized current flow
- Task:Determine a list of global connections and globalSteiner points in order to achieve an optimizedcurrent flow



# **Our Algorithm**



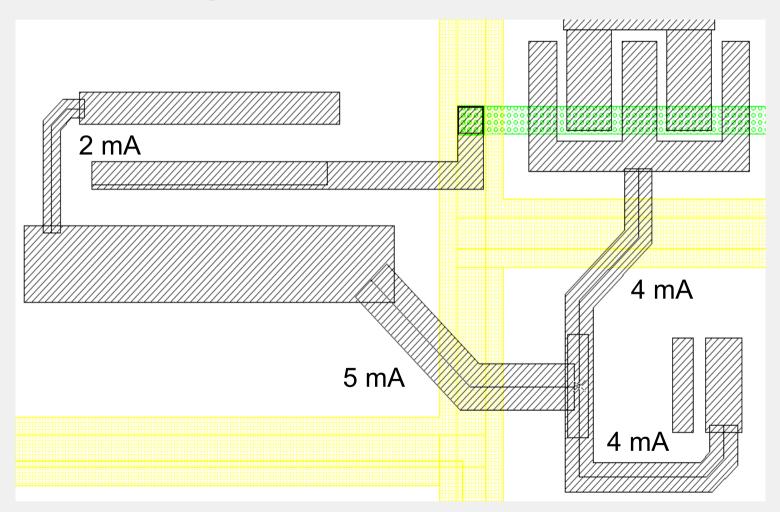
## Our Algorithm (cont.'d)



- 1. Create mesh graph
- 2. Choose start terminal T<sub>s</sub>
- 3. Get shortest edge for T<sub>s</sub>
- 4. Calculate CCA for active edge: A: 970 LU<sup>2</sup> B: 720 LU<sup>2</sup> C: 620 LU<sup>2</sup>

# **Our Algorithm**

#### **Detailed Routing Result**



#### Results

CELLS	METHOD	W IRE AREA $(\mu M^2)^*$	VIAS	ROUTING AREA (%)**	ROUTING TIME (MIN)
supply	Our approach	50,220	145	100	3
	M anually	51,440	138	102.6	≈ 125
	Steiner tree	n/a	149	102.0	22
	Terminal tree	n/a	148	102.2	4
wala	Our approach	76,337	136	100	3.5
	M anually	76,340	130	100.3	≈ 150
	Steiner tree	n/a	142	103.0	8
	Terminal tree	n/a	139	104.0	5
imux	Our approach	78,880	178	100	4.5
	M anually	80,320	178	103.4	≈ 180
	Steiner tree	n/a	198	103.8	9
	Terminal tree	n/a	193	103.9	5
receiver	Our approach	54,604	180	100	6
	M anually	58,380	178	102.5	≈ 185
	Steiner tree	n/a	199	102.0	13
	Terminal tree	n/a	197	102.8	7
dcdriver	Our approach	102,275	455	100	14
	M anually	108,880	460	104.1	≈ 240
	Steiner tree	n/a <sup>***</sup>	n/a***	n/a <sup>***</sup>	$n/a^{***}$
	Terminal tree	n/a	483	106.0	20

\* Wire Area = Current connection area (CCA) of all wires according to Equation (6)

*Routing Area = Die area used for routing Not applicable due to memory and run time limitations*

## Conclusion

- Presented new and effective method for current characterization
- Presented new strategy for fast current-driven wire planning based on segment allocation and hence, current calculation, prior to detailed routing
- Industrial usage showed very promising results and some important practical issues (e.g. inhomogeneous current flow, via array sizing, etc.)
- In future, reliability-related constraints (such as current strengths) must become an integral part of place/route/verification tools in order to fulfill reliability constraints